Dimension Reduction for Classification

Alfred O. Hero Dept. EECS, Dept BME, Dept. Statistics University of Michigan - Ann Arbor <u>hero@eecs.umich.edu</u> http://www.eecs.umich.edu/~hero

BIRS, July. 2005

- 1. The manifold supporting data sample
- 2. Classification constrained dimension reduction
- 3. Dimension estimation on smooth manifolds
- 4. Applications
- 5. Conclusions

1. Manifold supporting data sample



Yale Face Database B: each 128x128 image lies in R⁽¹⁶³⁸⁴⁾



Data-driven dimensionality reduction

- Data-driven dimensionality reduction consists of:
 - Estimation of intrinsic dimension d:
 - Direct intrinsic dimension estimation
 - Reconstruction of data samples in the manifold domain:
 - Manifold learning
- Classifiers on intrinsic data dimension
 - Estimated dimension as a discriminant
 - Label-constrained manifold learning

Manifold Learning

Manifold learning problem setup:

Given a finite sampling $\mathcal{Y}_n = \{\mathbf{Y}_1, \dots, \mathbf{Y}_n\} \subset \mathbb{R}^D$ of a *d*-dimensional manifold $\mathcal{M} \subset \mathbb{R}^D$ find an embedding of \mathcal{Y}_n into a subset $\mathcal{X}_n = \{\mathbf{X}_1, \dots, \mathbf{X}_n\} \subset \mathbb{R}^d$ (usually $d \ll D$) without any prior knowledge about \mathcal{M} or d.



Manifold learning background

Reconstructing the mapping and attributes of the manifold from a finite dataset falls into the general manifold learning problem.

Manifold reconstruction for fixed d:

- 1. ISOMAP, Tenenbaum, de Silva, Langford (2000);
- 2. Locally Linear Embeddings (LLE), Roweiss, Saul (2000);
- 3. Laplacian Eigenmaps, Belkin, Niyogi (2002);
- 4. Hessian Eigenmaps (HLLE), Grimes, Donoho (2003);
- 5. Local Space Tangent Alignment (LTSA), Zhang, Za (2003);
- 6. SemiDefinite Embedding (SDE), Weinberger, Saul (2004).



Laplacian Eigenmaps

Laplacian Eigenmaps: preserving local information (Belkin & Niyogi 2002)

1. Constructing an Adjacency Graph:

a. compute a k-NN graph on the dataset;



b. compute a similarity/weight matrix W between data points, that encodes neighborhood information (e.g., heat kernel):

$$w_{ij} = \begin{cases} e^{-\frac{|\boldsymbol{y}_i - \boldsymbol{y}_j|^2}{\epsilon}} & \text{, if } \boldsymbol{y}_i, \boldsymbol{y}_j \text{ are } k\text{-NN} \\ 0 & \text{, o.w.} \end{cases}$$

Laplacian Eigenmaps

- 2. Manifold learning as an optimization problem:
 - a. objective function:

$$E(\mathcal{X}_n) = \sum_{ij} w_{ij} |\boldsymbol{x}_i - \boldsymbol{x}_j|^2 = 2 \operatorname{tr} \left(X L X^T \right) \;,$$

where
$$L = D - W \left(D = \operatorname{diag} \left\{ \sum_{j} W_{ji} \right\} \right)$$

is the Graph Laplacian.

b. embedding is solution of

$$\begin{array}{c} \min_{\substack{X \ D \ 1 = 0 \\ X \ D \ X^T = I}} \operatorname{tr} \left(X \ L \ X^T \right) \\ (*)$$

Laplacian Eigenmaps

3. Eigenmaps:

 a. solution to (*) is given by the *d* generalized eigenvectors associated with the *d* smallest generalized eigenvalues that solve:

$$L \boldsymbol{v} = \lambda D \boldsymbol{v}$$

equivalently, eigenvectors of the normalized Graph Laplacian

$$\tilde{L} = D^{-1/2} L D^{-1/2}$$

b. if $V = [v_1 \dots v_m]$ is the collection of such eigenvectors, then the embedded points are given by

$$oldsymbol{x}_i = (v_{i1}, \ldots, v_{im})^T \ , \ 1 \leq i \leq n$$

Dimension Reduction for Labeled Data



2. Classification constrained dimensionality reduction

Adding class dependent constraints - "virtual" class vertices.



Label-penalized Laplacian Eigenmaps

1. If C is the class membership matrix (i.e., c_ij = 1 if point j is from class i), define the objective function:

$$E(\mathcal{Z}_n) = \sum_{ki} c_{ki} |oldsymbol{z}_k - oldsymbol{x}_i|^2 + eta \sum_{ij} w_{ij} |oldsymbol{x}_i - oldsymbol{x}_j|^2 \;,$$

where $Z_n = \{z_1, z_2, x_1, \dots, x_n\}, z_1, z_2$ are the "virtual" class centers and $\beta \ge 0$ is a regularization parameter.

2. Embedding is solution of

$$\min_{\substack{ZD1=0\\ZDZ^T=I}} \operatorname{tr} \left(ZLZ^T \right) ,$$

 $\begin{bmatrix}
I & C \\
C^T & \beta W
\end{bmatrix}$

where L is Laplacian of augmented weight matrix K =



Partially Labeled Data

Semi-Supervised Learning on Manifolds



Semisupervised extension

Algorithm:

- 1. Compute the constrained embedding of the entire data set, inserting a zero column in *C* for each unlabeled sample.
- 2. Fit a (e.g., linear) classifier to the labeled embedded points by minimizing the quadratic error loss:

$$\ell(\boldsymbol{a}) = \sum_{\substack{i : \boldsymbol{y}_i \text{ is } \\ \text{labeled}}} \left(c_i - \boldsymbol{a}^T \boldsymbol{x}_i \right)^2$$

3. For an unlabeled point, label it using the fitted (linear) classifier:

$$c_j = \left\{egin{array}{c} 1 & ext{if } oldsymbol{a}^T oldsymbol{x}_j \geq 0 \ -1 & ext{if } oldsymbol{a}^T oldsymbol{x}_j < 0 \end{array}
ight.$$

Classification Error Rates



Percentage of errors for labeling unlabeled samples as a function of the number of labeled points, out of a total of

1000 points on the Swiss roll.

3. Methods of dimension estimation

- Scree plots g(u) = u, f(x) = c
 - Plot residual fitting errors of SVD, Isomap, LE, LLE



ISOMAP residual curve

$$g(u) = u, f(x) = c$$

- Box counting, sphere packing (Liebovitch and Toth)

Kolmogorov/Entropy/Correlation dimension

$$d = \lim_{r \to 0} \frac{\log N(r)}{\log(1/r)}$$

- Maximum likelihood g(u) = u, f(x) = c
 - Poisson approximation to Binomial (Levina&Bickel:2004)

$$\frac{k}{n} \approx f(x_o) V(d) ||x_o - x_{(k)}^{x_o}||^d$$

• Entropic graphs $g(u) = u^{\alpha}$

•

 Spanner-graph length approximation to entropy functional (Costa&Hero:2003)

$$L_n(\mathcal{X}_n)/n^{(d-1)/d} \to \beta_d \int_{\mathcal{M}} f^{\alpha}(x) dx$$

Euclidean Random Graphs

- $\mathcal{X}_n = \{X_1, \dots, X_n\}$ data in D-dimensional Euclidean space
- Euclidean MST with edge power weighting gamma:

$$L_{\gamma}(\mathcal{X}_n) = \min_{E \in \mathcal{E}} \sum_{|e| \in E} |e|^{\gamma}$$

- ${\mathcal E}$ pairwise distance matrix over ${\mathcal X}_n$
- E edge length matrix of spanning trees over \mathcal{X}_n
- Euclidean k-NNG with edge power weighting gamma:

$$\mathcal{L}_{k,\gamma}(\mathcal{X}_n) = \sum_{i=1}^n \sum_{|e| \in E_k(X_i)} |e|^{\gamma}$$

Example: Uniform Planar Sample



University of

Convergence of Euclidean CQF's



Beardwood, Halton, Hammersley Theorem (BHH:1959): $L_{\gamma}(\mathcal{X}_n)/n^{lpha} o eta_d \ \int_{R^d} \ f^{lpha}(x) dx$ $lpha = (d-\gamma)/d$

k-NNG Convergence Theorem in Non-Euclidean Spaces

Let \mathcal{M} be a compact smooth Riemann *d*-dimensional manifold embedded in \mathbb{R}^D . Let $2 \leq d \leq D$ and $0 < \gamma < d$. Suppose that X_1, \ldots, X_n are i.i.d. random vectors on \mathcal{M} with common bounded density *f* relative to $\mu_{\mathcal{M}}$. Then the total length of the k-NNG satisfies

$$L_{\gamma}(\mathcal{X}_n)/n^{(d'-\gamma)/d'}
ightarrow \left\{ egin{array}{ccc} \infty, & d' < d \ eta_d \int_{\mathcal{M}} f^{lpha}(x) \, \mu_{\mathcal{M}}(dx), & d' = d \ 0, & d' > d \end{array}
ight.,$$

(a.s) where $\alpha = (d - \gamma)/d$. Costa, Hero: TSP(2004), Birkhauser(2005) NUMBER OF CORRECT DIMENSION ESTIMATES OVER 30 TRIALS AS A FUNCTION OF THE NUMBER OF SAMPLES FOR THE

TORUS (N = 5, Q=10).

n	200	400	600
GMST	29	30	30
5-NN	29	30	30

2.

2.

average length N

2.

2.

2.

TABLE II

Entropy estimates for the torus (n = 600, N = 5, Q=10).

	emp. mean	std. deviation
GMST	10.0	0.55
5 - NN	9.6	0.93



Local Extension via kNNG

- Initialize: $x_o \in \mathcal{X}_n$, $\mathcal{A}_{1,x_o} = \mathcal{N}_{k,x_o}$
- For i=1,2,...p

• $\forall x_j \in \mathcal{A}_{i,x_o}$ compute \mathcal{N}_{k,x_j} and set

$$\mathcal{A}_{i+1,x_o} = \cup_{x_j} \mathcal{N}_{k,x_j} \cup \mathcal{A}_{i,x_o}$$



4. Application to MNIST Digits

- Large database of 8 bit images of digits 0-9.
- 28x28 pixels for each image
- First 1000 images in training set used here
- Non-adaptive: digit labels are known



Scree Plot



Local Dimension/Entropy Statistics





Costa&Hero:Birkhauser05











Univer













Adaptive Anomaly Detection

• Spatio-temporal measurement vector:

$$\mathbf{x}(t) = [\mathbf{x}_1(t), \dots, \mathbf{x}_N(t)] \quad \forall t = 1 \dots \tau$$



Data Observed from Abilene Network

- Objective: detect changes in network traffic via local intrinsic dimension
- Hypotheses:
 - High traffic from few sources lowers the local dimension of the network traffic
 - Changes in distribution of dimension estimate can be used as a marker for more subtle changes in traffic
- Data collection period: 1/1/05-1/2/05
- Data sampling: packet flow sampled every 5 minutes from all 11 routers on Abilene Network
- Data fields: aggregate of all flows to/from all ports

KNN Algorithm (Costa)



Example – 1/1/05, 12:20 pm

• Large data transfers from IPs 145.146.96 and 192.31.120 drastically increase flows through Chicago and NYC.



5. Conclusions

- Classification constraints can be included in manifold learning dimension reduction algorithms
- kNNG jointly estimate dimension and entropy of high dimensional data
- Dimension can be used as a discriminant in anomaly detection
- Can be used as precursor to model reduction and database compression
- Methods only suffer from curse of *intrinsic* dimensionality

References

- J. Costa, N. Patwari and A. O. Hero, "Distributed multidimensional scaling with adaptive weighting for node localization in sensor networks", (<u>http://www.eecs.umich.edu/~hero/Preprints/wmds_v9.pdf</u>), ACM Journal on Networking To appear 2005.
- J. Costa and A. O. Hero, "Geodesic entropic graphs for dimension and entropy estimation in manifold learning," (http://www.eecs.umich.edu/~hero/Preprints/sp_mlsi_final_twocolumn.pdf), IEEE Trans. on Signal Process., Vol. 52, No. 8, pp. 2210-2221, Aug. 2004.
- J.A. Costa, A. Girotra and A.O. Hero, "Estimating Local Intrinsic Dimension with k-Nearest Neighbor Graphs," IEEE Workshop on Statistical Signal Processing (SSP), Bordeaux, July 2005. (http://www.eecs.umich.edu/~hero/Preprints/ssp 2005 final 1.pdf)
- J. Costa and A. O. Hero, "Classification constrained dimensionality reduction,"

(http://www.eecs.umich.edu/~hero/Preprints/costa_icassp2005.pdf), Proc. of ICASSP, Philadelphia, March, 2005.